

SEMESTER <i>Fifth</i>	DEPARTMENT <i>Control Engineering</i>	COURSE TITLE <i>Control Theory I Lab.</i>
COURSE CODE <i>EC506</i>	HOURS 3 UNITS 1	COURSE SPECIFICATIONS <i>Practical Content</i>
1. The Fundamental Components of the Control System: <ul style="list-style-type: none"> ➤ Introduction to control valves, electric motors, sensors and transducers. ➤ Linear time-invariant systems and representation. ➤ Performance of open loop control system: Liquid- level control system. 		
2. Control System Analysis: <ul style="list-style-type: none"> ➤ Step response of open-loop control system. ➤ Response analysis of open- loop control system: (time delay, gain, and settling time). ➤ Open loop step response analysis for DC motor control. 		
3. Closed Loop Systems: <ul style="list-style-type: none"> ➤ Closed loop position control system design. ➤ Effect of Feedback on disturbance & Control System Design. 		
4. PID Controller: <ul style="list-style-type: none"> ➤ Description of characteristics of the P-controller, PI-controller, and PID-controller. ➤ The effect of P controller and PI controller on different closed loop systems: <ul style="list-style-type: none"> ○ Temperature system. ○ DC motor control system. ○ Liquid- level control system. ➤ The effect of adding D controller. 		
5. Application of a PID Controller: <ul style="list-style-type: none"> ➤ Response requirements. ➤ The parameters of the PID controller to meet the response. ➤ Building PID controller using analogue and digital electronic. 		

References:

1. ***Modern Control Engineering***, K. Ogatta, Prentice Hall, 1994.
2. ***Modern Control Systems***, R. C. Dorf, Eddison Wesley, 1990.